SE420 Laboratory Assignment 2
Introduction to TMS320F28379D GPIO Programming and Texas Instruments Code Composer Studio

Goals for this Lab Assignment:
1. Use CPU Timer to periodically perform desired procedures/code.
2. Work with port inputs and port outputs.
3. What to do with a compiler error.
4. Debugging your source code with Breakpoints and the Watch Window.

Library Functions Used:
- (none)

Matlab Functions Used:
- (none)

Prelab:
Complete: http://coeecs.ece.illinois.edu/ge420/GE420Lab2ExtraPrelab.pdf

LED’s Default GPIO Assignments:

<table>
<thead>
<tr>
<th>LED</th>
<th>GPIO, Controlled with Registers GPADAT, GPASET, GPACLEAR and GPATOGGLE</th>
</tr>
</thead>
<tbody>
<tr>
<td>LED1</td>
<td>GPIO22, Controlled with Registers GPADAT, GPASET, GPACLEAR and GPATOGGLE</td>
</tr>
<tr>
<td>LED2</td>
<td>GPIO52, Controlled with Registers GPBDAT, GPBSET, GPBCLEAR and GPBTOGGLE</td>
</tr>
<tr>
<td>LED3</td>
<td>GPIO67, Controlled with Registers GPCDAT, GPCSET, GPCCLEAR and GPCTOGGLE</td>
</tr>
<tr>
<td>LED4</td>
<td>GPIO94, Controlled with Registers GPCDAT, GPCSET, GPCCLEAR and GPCTOGGLE</td>
</tr>
<tr>
<td>LED5</td>
<td>GPIO95, Controlled with Registers GPCDAT, GPCSET, GPCCLEAR and GPCTOGGLE</td>
</tr>
<tr>
<td>LED6</td>
<td>GPIO97, Controlled with Registers GPDDAT, GPDSET, GPDCLEAR and GPDTOGGLE</td>
</tr>
<tr>
<td>LED7</td>
<td>GPIO111, Controlled with Registers GPDDAT, GPDSET, GPDCLEAR and GPDTOGGLE</td>
</tr>
<tr>
<td>LED8</td>
<td>GPIO130, Controlled with Registers GPEDAT, GPESET, GPECLEAR and GPETOOGLE</td>
</tr>
<tr>
<td>LED9</td>
<td>GPIO131, Controlled with Registers GPEDAT, GPESET, GPECLEAR and GPETOOGLE</td>
</tr>
<tr>
<td>LED10</td>
<td>GPIO131, Controlled with Registers GPEDAT, GPESET, GPECLEAR and GPETOOGLE</td>
</tr>
<tr>
<td>LED11</td>
<td>GPIO131, Controlled with Registers GPEDAT, GPESET, GPECLEAR and GPETOOGLE</td>
</tr>
<tr>
<td>LED12</td>
<td>GPIO6, Controlled with Registers GPADAT, GPASET, GPACLEAR and GPATOGGLE</td>
</tr>
<tr>
<td>LED13</td>
<td>GPIO07, Controlled with Registers GPADAT, GPASET, GPACLEAR and GPATOGGLE</td>
</tr>
<tr>
<td>LED14</td>
<td>GPIO8, Controlled with Registers GPADAT, GPASET, GPACLEAR and GPATOGGLE</td>
</tr>
<tr>
<td>LED15</td>
<td>GPIO9, Controlled with Registers GPADAT, GPASET, GPACLEAR and GPATOGGLE</td>
</tr>
<tr>
<td>LED16</td>
<td>GPIO24, Controlled with Registers GPADAT, GPASET, GPACLEAR and GPATOGGLE</td>
</tr>
<tr>
<td>LED17</td>
<td>GPIO25, Controlled with Registers GPADAT, GPASET, GPACLEAR and GPATOGGLE</td>
</tr>
<tr>
<td>LED18</td>
<td>GPIO26, Controlled with Registers GPADAT, GPASET, GPACLEAR and GPATOGGLE</td>
</tr>
<tr>
<td>LED19</td>
<td>GPIO27, Controlled with Registers GPADAT, GPASET, GPACLEAR and GPATOGGLE</td>
</tr>
<tr>
<td>LED20</td>
<td>GPIO60, Controlled with Registers GPBDAT, GPBSET, GPBCLEAR and GPBTOGGLE</td>
</tr>
<tr>
<td>LED21</td>
<td>GPIO61, Controlled with Registers GPBDAT, GPBSET, GPBCLEAR and GPBTOGGLE</td>
</tr>
<tr>
<td>LED22</td>
<td>GPIO157, Controlled with Registers GPEDAT, GPESET, GPECLEAR and GPETOOGLE</td>
</tr>
<tr>
<td>LED23</td>
<td>GPIO158, Controlled with Registers GPEDAT, GPESET, GPECLEAR and GPETOOGLE</td>
</tr>
</tbody>
</table>
Push Button’s Default GPIO Assignments:

<table>
<thead>
<tr>
<th>GPIO Pin</th>
<th>Default Assignment</th>
</tr>
</thead>
<tbody>
<tr>
<td>PB1</td>
<td>GPIO122, Read bit status with Register GPDDAT</td>
</tr>
<tr>
<td>PB2</td>
<td>GPIO123, Read bit status with Register GPDDAT</td>
</tr>
<tr>
<td>PB3</td>
<td>GPIO124, Read bit status with Register GPDDAT</td>
</tr>
<tr>
<td>PB4</td>
<td>GPIO125, Read bit status with Register GPDDAT</td>
</tr>
</tbody>
</table>

**GPIO Register Use when GPIO pin set as Output:** The GPIO Registers are 32 bit registers but we use unions and bitfields in the C/C++ programming language to control just one bit of the 32 bit register at a time. The “.all” part of the C/C++ union is the entire 32bit register. The “.bit.GPIO19” is just one bit in the 32 bit register. So these two lines of C code perform the same operation:

GpioDataRegs.GPASET.all = 0x00000800; //You have to think a bit with this code to know that bit 11 is being set.
GpioDataRegs.GPASET.bit.GPIO11 = 1; //This line of code is easier to understand that we are setting the 11th bit.

<table>
<thead>
<tr>
<th>Register</th>
<th>Usage</th>
<th>Example</th>
</tr>
</thead>
</table>
| GP?DAT   | GP?DAT.bit.GPIO? = 1, Sets that Pin High, 3.3V  
           GP?DAT.bit.GPIO? = 0, Sets that Pin Low, 0V/GND | GpioDataRegs.GPADAT.bit.GPIO19 = 1; Sets GPIO19 High/3.3V  
           GpioDataRegs.GPADAT.bit.GPIO19 = 0; Sets GPIO19 Low/0V |
| GP?SET   | GP?SET.bit.GPIO? = 1, Sets that Pin High, 3.3V  
           GP?SET.bit.GPIO? = 0, Does Nothing | GpioDataRegs.GPSET.bit.GPIO37 = 1; Sets GPIO37 High/3.3V  
           GpioDataRegs.GPSET.bit.GPIO37 = 0; Does Nothing |
| GP?CLEAR | GP?CLEAR.bit.GPIO? = 1, Sets that Pin Low, 0V/GND  
           GP?CLEAR.bit.GPIO? = 0, Does Nothing | GpioDataRegs.GPCCLEAR.bit.GPIO70 = 1; Sets GPIO70 Low/0V  
           GpioDataRegs.GPCCLEAR.bit.GPIO70 = 0; Does Nothing |
           GP?TOGGLE.bit.GPIO? = 0, Does Nothing | GpioDataRegs.GPDTOGGLE.bit.GPIO98 = 1; was 3.3V then 0V or was 0V then 3.3V  
           GpioDataRegs.GPDTOGGLE.bit.GPIO98 = 0; Does Nothing |

**GPIO Register Use When GPIO Pin Set as Input:** Each GPIO pin, when setup as an input, has an internal pull-up resistor that can either enabled/connected or disabled/disconnected to that GPIO pin. With the passive push button on our breakout board, we will need to enable the pull-up resistor.

<table>
<thead>
<tr>
<th>Register</th>
<th>Usage</th>
<th>Example</th>
</tr>
</thead>
</table>
| GP?DAT   | If GP?DAT.bit.GPIO? is equal to 1 then the Pin is High, 3.3V  
           If GP?DAT.bit.GPIO? is equal to 0 then the Pin is Low, 0V/GND | if (GpioDataRegs.GPADAT.bit.GPIO19 == 1) {  
           //code that needs to run when input pin GPIO19 is High/3.3V  
       } else {  
           // code that needs to run when input ping GPIO19 is Low/0V  
       } |

**Laboratory Exercises**

**Exercise 1:**

First, make sure your repository is up to date. Under Lab 1, find the Git help file titled “Using the SE420 Repository” and read and perform the steps of the last section of the document titled “Course File Updates.” These steps will pull the latest updates from the class repository you forked in Lab 1. This procedure can be a bit confusing so ask your TA for help if needed. You should perform these steps each time you come to a new lab session to make sure you have the latest starter code.

Now that you have the updates, create a new project in your workspace and call it lab2. If you forget the steps of importing the labstarter project and renaming the project and files with lab2 names, see the lab 1 document. Once you have your new lab 2 project perform the below steps.
1. For this lab, you will only be using CPU Timer 2’s interrupt service routine “cpu_timer2_isr(void)”. We will leave the timer0 and timer1 functions in our source code but we will not enable timer0 or timer1. So in main() find the two lines of code that set the TIE bit to enable timer 0 and timer 1. Comment these two lines so they are not included in your program. i.e.

```
//CpuTimer0Regs.TCR.all = 0x4000;
//CpuTimer1Regs.TCR.all = 0x4000;
```

2. In main() find the “ConfigCpuTimer” function call for CPU Timer 2 and set its period to 0.25 seconds. Also find CPU Timer 2’s interrupt function “cpu_timer2_isr.” Note that in this function, it is blinking on and off six LEDs on the break out board and the blue LED on the Launchpad. Build and Debug this code to make sure that the code compiles and runs. You should see the blue LED along with the second LED row blinking on and off every half second. Once that is working, terminate your debug session and go to the next step.

3. In the cpu_timer2_isr function, comment out the lines of code that toggle the row of LEDs on and off. Leave the line that toggles GPIO31. Create a global int32_t variable and name it something like “numTimer2calls.” Inside the cpu_timer2_isr function increment that variable by one each time that function is entered. In addition, every time the function is entered, set the already defined global variable “UARTPrint” to 1. By doing this you are telling the main() while loop to print text through a UART serial port to your PC. Find this serial_printf() function call in the main() while loop. Does it make sense that when you set “UARTPrint” to 1, then the while loop calls the serial_printf function? Why is UARTPrint set to zero inside the if after serial_printf is called? Change the text so that it prints your “numTimer2calls” global variable. Since “numTimer2calls” is a 32 bit integer you will need to use the %ld formatter. Also have the serial_printf() function print the value of the numRXA variable just as it does in the default serial_printf() statement. You should not print the numSWIcalls variable because the SWI is not being used.

   To see this printed text you need to install a serial terminal on you PC. Tera Term is installed on the Windows machines in lab. On Mac do a web search for Serial Terminal for Mac. We need to figure out what serial port COM number your USB serial port is using. The easiest way to find this is to run “Device Manager” in Windows and find the “Ports” item. Under ports find the COM number for the device titled “XDS100 Class USB Serial Port”. Run Tera Term and select the “Serial” item and find the XDS100 COM port in the list of COM ports. Final thing to do is change the Baud (or Bit) speed of the COM port. Still in Tera Term select the menu item “Setup” and then “Serial Port…”. Change the “Speed” to 115200 if it is not already. Build and Debug your code and check that the LaunchPad’s blue LED is still blinking and your text is printing to Tera Term. So your TA this working. Also have your TA show you how to increment the “numRXA” variable that you are printing. We will not use this in this lab, but just wanted to show that the UART is receiving characters along with transmitting characters.

4. Write two worker functions “void SetLEDColumnsOnOff(int16_t columns)” and “int16_t ReadSwitches(void)”.
   • void SetLEDColumnsOnOff(int16_t columns) takes an 16 bit integer as a parameter. The four least significant bits of this integer determine if the four LED columns are on or off. Bit 0 determines the right most column’s state. Bit 1 determines the right middle column’s state. Bit 2 determines the left middle column’s state. Bit 3 determines the left most column’s state. So for example if 6 (which is binary 0110) is passed to your function then both the middle columns of LEDs should be lit and the left and right column of
LEDs should be off. Use four if statements inside your function to check, using the bitwise AND, &, operator, if the integer passed to your function has the least significant four bits either individually set or cleared. If set, turn ON the corresponding column. If cleared, turn OFF the corresponding column. See the above tables for definitions and example code on writing to the registers that control the LEDs. Also, the default C code that toggles the LEDs on and off in the timer_isr functions should help. Here though, I want you using the GP?SET and GP?CLEAR registers to turn on or off the LEDs.

- int16_t ReadSwitches(void) returns a 16 bit integer that the least significant four bits indicates the state of the four switches. (Note that when each of the switches are not pressed the GPIO pin reads a 1 or high voltage. When pressed the GPIO pin read a 0 or ground. This is because the IO pin is using an internal pullup resistor.) This function should have four if statements and use the bitwise OR, "|" operator to create this return value. So start the return value at zero. Then if switch 1 is pressed OR 0x1 with value. If switch 2 is pressed OR 0x2 with value. If switch 3 is pressed OR ??? with value. If switch 4 is pressed OR ??? with value. Finally return the value with the return() function call. See the above table for the GPIO pins that are connect to the push buttons and that are setup as inputs with pull-up resistor in the default code.

5. Now that you have these worker functions, make your program a bit more interesting. Add code in your CPU timer 2 interrupt function so that you print the value returned from your ReadSwitches() function by assigning a global int16_t variable to the value of ReadSwitches() and print this additional value in your serial_printf function in main()'s while loop. Also pass this value that is returned from your ReadSwitches() function to your SetLEDColumnsOnOff(value) function. This way the LED columns will indicate the state of the switches. Show this working to your TA.

Exercise 2:

1. To get some more practice with starting a new project, create another new project by importing the labstarter example and renaming it and its main source file. Again, disable CPU timer0 and timer1’s interrupt by commenting out:

   //CpuTimer0Regs.TCR.all = 0x4000;
   //CpuTimer1Regs.TCR.all = 0x4000;

   Change the period of CPU timer 2 to 0.25 seconds. Also copy from your previous project the two worker functions you created. Do not modify these worker functions. Instead use them in the below steps.

2. Change the code in cpu_timer2_isr to increment a global 32 bit integer (you created) by 1 every time timer 2’s interrupt function is called. Pass this count variable to the SetLEDColumnsOnOff() function to display the least significant 4 bits of your count variable to the four LED columns. Compile, download to the DSP and verify that indeed the LED columns are counting in binary. Add one more item to this code as an exercise to see the use of bitwise operators in C. Using the ReadSwitches() function, an “if” statement and one or more of the bitwise C operators &, |, ~, check if push button 2 is pressed. If pushbutton 2 is pressed, stop incrementing the global count integer. If pushbutton 2 is released, continue counting. Again compile and download to the DSP. When you code is working demonstrate your application to your TA.

Exercise 3: Breakpoints and Watch Windows
Starting with the code you just finished, we want to experiment with adding breakpoints to your code and using the “Expressions window” to edit the values of your variables.

1. In your previous code (with the DSP halted), put your cursor over the integer variable that you are incrementing. You should see that the value of the variable appears. Run your code, halt it again, and again put your cursor over the variable to confirm that it changes.

2. An easier method than using the cursor repeatedly is to add the variable to the Expressions window. When the DSP is halted, the Expressions window displays the current value of each variable in the Expressions window. To add your counting integer variable to the Expressions window, highlight the variable and then right-click, then select **Add Watch Expression…** The variable will appear in the Expressions window with the current value of the variable. The Expressions window dialog is also found under the View menu.

3. Next play a bit with adding breakpoints and single stepping through a section of code. The code you have written to this point is very small. Add the following nonsense code to allow for easy use of breakpoints and code stepping. At the top of your C-file, but below the #includes, add the following global variables:
   
   ```c
   float x1 = 6.0;
   float x2 = 2.3;
   float x3 = 7.3;
   float x4 = 7.1;
   
   Then inside your CPU timer 2 interrupt function add this nonsense code:
   ```
   
   ```c
   x4 = x3 + 2.0;
   x3 = x4 + 1.3;
   x1 = 9*x2;
   x2 = 34*x3;
   ```
   
   Build and load your code. Add a breakpoint to your code by double clicking on the left gray margin of your source file. A breakpoint is a location where the program will literally halt during execution. This allows you to check the values of your variables during operation. After a breakpoint, you can single step through your code (F5) and watch the variables update as different calculations are performed. You remove breakpoints by again clicking in the left gray margin.

4. If you happened not to receive any compiler errors during any of the above exercises, you should intentionally add some errors to your code so that you will see how CCS will alert you during the build process. Try double clicking on the error message. The editor will then take you to the line of code that has the error.

**Exercise 4:**

Write a program that spells out a 3 or 4 letter word in Morse code using all 23 LEDs as one light source. See [http://en.wikipedia.org/wiki/Morse_code](http://en.wikipedia.org/wiki/Morse_code) for specifics on Morse code. Here I want you using an int16_t array to indicate to your CPU timer 2 interrupt function whether it should turn all 23 LEDs or turn off all 23 LEDs. Each time into the CPU timer 2 interrupt function, check an index into the array. If the value at that index is set to 1, then turn on all 23 LEDs. If the value at that index is 0, turn off all LEDs. Then before exiting from CPU timer 2’s interrupt function, increment the index by one so that the next time into the interrupt you will be looking at the next index in your array. Your array will
have a certain length. Make sure not to increment past the length of your array by setting the index to zero when index has reached the size of your array. This will cause your Morse code communication to start from the beginning. Below is an example array for “S O S”.

```c
int16_t morse[34] = {1,0,1,0,0,0,1,1,1,1,0,1,1,1,0,0,0,1,0,1,0,0,0,0,0,0,0,0};
```

Demo this to your TA.

**Take Home Exercise:**

Using the ReadSwitches() function you created above, have the CPU timer 2 interrupt function check the status of the 4 pushbuttons every 100ms. Then pass the value returned from ReadSwitches() to a new “worker” function that you need to create that prints a 0, 1, 2, 3, 4, 5, 6, 7, 8, 9, A, B, C, D, E, F character to the 23 LEDs. For example if 2 is passed to this new function, it should turn on the LEDs in this pattern: (Black is LED on)

If you would like to choose a different pattern for 2 that would be fine also. I have grids labeling the LED numbers to help you sketch the other hex digits.

**Lab Check Off:**

1. Demonstrate your first application that continually checks the status of the four pushbuttons and displays their current state on the four LED columns.
2. Demonstrate your second application that updates a counter every quarter second and outputs the least significant 4 bits of the count to the four LED columns. The count should stop if pushbutton 2 pressed and resume when it is released.
3. Demonstrate that you know how to use Breakpoints and the Watch Window to debug your source code.
4. Demonstrate your Morse code application.

**Take Home Exercise:** Due before the next lab. Commented code and Video of code working submitted to your individual Box folder that I created for you for submissions.