## Prelaboratory Exercise 1

## Objectives

In this Prelab, you will complete the first two steps required to simulate systems in Simulink:

- 1. Determine the governing equation(s) of a system.
- 2. Draw out the block diagram representing the system dynamics on paper.

## Assignment

We will consider two systems (shown in Figures 1 & 2) for simulation. During Lab 1, you will use your results from this Prelab to build and run the simulations in Simulink. Complete the following questions in the space provided.



Figure 1: A Mass-Spring-Damper System

**1.** Derive the equation(s) of motion for the mass-spring-damper system pictured in Figure 1. Use the system parameter values provided.

**2.** From the equation(s) of motion, draw a block diagram of the system. *Hint:* Rearrange the equation(s) in Question 1 to express the highest derivative term as a function of the lower derivative terms.



Figure 2: A Pendulum with Viscous Damping

**3.** Derive the equation(s) of motion for the pendulum with viscous damping shown in Figure 2. Use the system parameter values provided.

**4.** Draw a block diagram for the equation(s) of motion you derived in Question 3. Assume that you are provided with a nonlinear block which can evaluate trigonometric functions.

5. Linearize the equation(s) of motion you derived in Question 3 for small  $\theta$ . Note: The small angle approximation is a 1<sup>st</sup>-order Taylor Series approximation.